

485 Transceivers

Feature

- Fail-safe circuitry
- Low power consumption
- Up to 256 transceivers can be attached to the bus
- Maximum transmission rate: 10Mbps(V_{cc}=5V)
- ESD: $\geq \pm 15kV$
- SOP8 Package

Applications

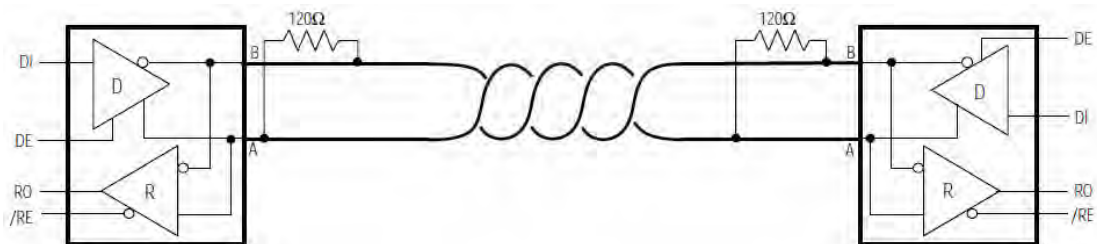
- RS485 Communications
- Level Translators
- Security Equipment
- Industrial Control Equipment
- Watt-hour meter

General Description

The FC485 is high-speed transceivers for RS-485 communication, which contain one driver and one receiver. The FC485 feature fail-safe circuitry, which guarantees a logic-high receiver output when the receiver inputs are open or shorted. This means that the receiver output will be a logic high if all transmitters on a

terminated bus are disabled (high impedance). The FC485 driver slew rates are not limited, making transmit speeds up to 10Mbps possible.. And this device has a 1/8-unit-load receiver input impedance that allows up to 256 transceivers on the bus.

Typical application circuit





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Absolute Maximum Ratings (TA=25°C)

Supply Voltage (VCC)+7V	Receiver Input Voltage (A,B) ±13V
Operating voltage ¹+3~5.5V	Receiver Output Voltage (RO) -0.3~Vcc+0.3V
Control Input Voltage (/RE, DE) -0.3~Vcc+0.3V	Operating Temperature (TOPR) -40°C~+105°C
Driver Input Voltage (DI) -0.3~Vcc+0.3V	Storage Temperature (TSTG) -65°C~+150°C
Driver Output Voltage (A,B) ±13V	

Note1: Recommended operating voltage is 5V, but can be compatible with 3V. If using a 3V or 3.3V supply voltage, please reduce the transmission rate.

DC ELECTRICAL CHARACTERISTICS (VCC=5.0V, TA=25°C) ¹

PARAMETER	SYMBOL	CONDITIONS		MIN	TYP	MAX	UNITS
Differential Driver Output (no load)	V _{OD1}	R=27Ω, Figure 1		---	---	VCC	V
Differential Driver Output	V _{OD2}			1.5	---	---	V
Change in Magnitude of Differential Output Voltage	ΔV _{OD}			---	---	0.2	V
Driver Common-Mode Output Voltage	V _{OC}			1.0	---	3.0	V
Change in Magnitude of Common-Mode Voltage ²	ΔV _{OC}			---	---	0.2	V
Input High Voltage	V _{IH}	DE, DI, /RE		2.0	---	---	V
Input Low Voltage	V _{IL}	DE, DI, /RE		---	---	0.8	V
DI Input Hysteresis	V _{HYS}	---		---	100	---	mV
Driver Input Current (A And B)	I _{IN1}	V _{IN} =12V	DE=0V, V _{CC} =5.0V	---	---	250	uA
		V _{IN} =-7V		-150	---	---	uA
Driver Short-Circuit Output Current ³	I _{OSD}	A and B Short-Circuit		-100	---	100	mA
Receiver Differential Threshold Voltage	V _{TH}	-7V ≤ V _{CM} ≤ 12V		-200	-125	-50	mV
Receiver Input Hysteresis	ΔV _{TH}	---		---	40	---	mV
Receiver Output High Voltage	V _{OH}	I _O =-8mA		VCC-1	---	---	V
Receiver Output Low Voltage	V _{OL}	I _O =8mA		---	---	0.4	V
Three-State Output Current at Receiver	I _{OZR}	V _O =1V		-1	---	1	μA
Receiver Input Resistance	R _{IN}	-7V ≤ V _{CM} ≤ 12V		96	---	---	KΩ
Receiver Output Short-Circuit Current	I _{OSR}	0V ≤ V _{RO} ≤ VCC		±7	---	±100	mA
Supply Current	I _{CC}	DE=VCC	No Load	---	700	1200	μA
		DE=GND	/RE=DI=VCC/GND	---	600	1200	μA
Supply Current in Shutdown Mode	I _{SHDN}	DE=GND, /RE=VCC, DI=VCC/GND		---	---	3	μA



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DC ELECTRICAL CHARACTERISTICS (VCC=3.0V, TA=25°C) ¹

PARAMETER	SYMBOL	CONDITIONS		MIN	TYP	MAX	UNITS
Differential Driver Output (no load)	V _{OD1}	R=27Ω, Figure 1		---	---	VCC	V
Differential Driver Output	V _{OD2}			0.9	---	---	V
Change in Magnitude of Differential Output Voltage	ΔV _{OD}			---	---	0.2	V
Driver Common-Mode Output Voltage	V _{OC}			1.0	---	3.0	V
Change in Magnitude of Common-Mode Voltage ²	ΔV _{OC}			---	---	0.2	V
Input High Voltage	V _{IH}	DE, DI, /RE		1.5	---	---	V
Input Low Voltage	V _{IL}	DE, DI, /RE		---	---	0.6	V
DI Input Hysteresis	V _{HYS}	---		---	100	---	mV
Driver Input Current (A And B)	I _{IN1}	VIN=12V	DE=0V, VCC=3V	---	---	150	uA
		VIN=-7V		-150	---	---	uA
Driver Short-Circuit Output Current ³	I _{OSD}	A and B Short-Circuit		-100	---	100	mA
Receiver Differential Threshold Voltage	V _{TH}	---		-200	---	200	mV
Receiver Input Hysteresis	ΔV _{TH}	---		---	40	---	mV
Receiver Output High Voltage	V _{OH}	I _O =-8mA		VCC-1	---	---	V
Receiver Output Low Voltage	V _{OL}	I _O =8mA		---	---	0.6	V
Three-State Output Current at Receiver	I _{OZR}	V _O =1V		-1	---	1	μA
Receiver Input Resistance	R _{IN}	-7V ≤ V _{CM} ≤ 12V		96	---	---	KΩ
Receiver Output Short-Circuit Current	I _{OSR}	0V ≤ V _{RO} ≤ VCC		±7	---	±100	mA
Supply Current	I _{CC}	DE=VCC	No Load	---	---	1000	μA
		DE=GND	/RE=DI=VCC/GND	---	---	1000	μA
Supply Current in Shutdown Mode	I _{SHDN}	DE=GND, /RE=VCC, DI=VCC/GND		---	---	3	μA

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SWITCHING CHARACTERISTICS (VCC=5.0V, TA=25°C)

PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS
Driver Rise or Fall Time	t_R, t_F	Figure 3 and 5, $R_{DIFF}=54$ $C_{L1}=C_{L2}=100pF$	---	30	---	ns
Driver Input to Output	t_{PLH}, t_{PHL}		---	30	60	ns
Driver Output Skew $T_{DPLH} - T_{DPHL}$	t_{SKEW}		---	---	20	ns
Driver Enable time	t_{LZ}, t_{HZ}	Figure 4 and 6, $C_L=100pF$ (Receiver enabled)	---	---	70	ns
Driver Enable time	$t_{LZ(SHDN)},$ $t_{HZ(SHDN)}$	Figure 4 and 6, $C_L=100pF$ (Receiver disabled)	---	1400	3000	ns
Driver disable time	t_{LZ}, t_{ZL}	Figure 4 and 6, $C_L=100pF$	---	---	70	ns
Maximum Data Rate	F_{MAX}	---	10	---	---	Mbps
Receiver Rise or Fall Time	t_R, t_F	Figure 7	---	20	---	ns
Receiver propagation delay time	t_{PLH}, t_{PHL}		---	90	250	ns
$T_{RPLH}-T_{RPHL}$ Differential Receiver Skew	t_{SKD}		---	30	---	ns
Receiver enable time	t_{ZL}, t_{ZH}	Figure 2 and 8, $C_{RL}=15pF$ (Driver enabled)	---	30	70	ns
Receiver enable time	$t_{ZL(SHDN)},$ $t_{ZH(SHDN)}$	Figure 2 and 8, $C_{RL}=15pF$ (Driver disabled)	---	1400	3000	ns
Receiver disable time	t_{LZ}, t_{HZ}	Figure 2 and 8, $C_{RL}=15pF$	---	30	70	ns
Time to Shutdown	t_{SHDN}	---	---	200	600	ns



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SWITCHING CHARACTERISTICS (VCC=3.0V, TA=25°C)

PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS
Driver Rise or Fall Time	t_R, t_F	Figure 3 and 5, $R_{DIFF}=54$ $C_{L1}=C_{L2}=100pF$	---	30	---	ns
Driver Input to Output	t_{PLH}, t_{PHL}		---	30	60	ns
Driver Output Skew $ T_{DPLH} - T_{DPHL} $	t_{SKEW}		---	---	20	ns
Driver Enable time	t_{LZ}, t_{HZ}	Figure 4 and 6, $C_L=100pF$ (Receiver enabled)	---	---	70	ns
Driver Enable time	$t_{LZ}(SHDN),$ $t_{HZ}(SHDN)$	Figure 4 and 6, $C_L=100pF$ (Receiver disabled)	---	1600	3000	ns
Driver disable time	t_{LZ}, t_{ZL}	Figure 4 and 6, $C_L=100pF$	---	---	70	ns
Maximum Data Rate	F_{MAX}	---	10	---	---	Mbps
Receiver Rise or Fall Time	t_R, t_F	Figure 7	---	20	---	ns
Receiver propagation delay time	t_{PLH}, t_{PHL}		---	90	250	ns
$ T_{RPLH}-T_{RPHL} $ Differential Receiver Skew	t_{SKD}		---	30	---	ns
Receiver enable time	t_{ZL}, t_{ZH}	Figure 2 and 8, $C_{RL}=15pF$ (Driver enabled)	---	25	70	ns
Receiver enable time	$t_{ZL}(SHDN),$ $t_{ZH}(SHDN)$	Figure 2 and 8, $C_{RL}=15pF$ (Driver disabled)	---	1600	3000	ns
Receiver disable time	t_{LZ}, t_{HZ}	Figure 2 and 8, $C_{RL}=15pF$	---	30	70	ns
Time to Shutdown	t_{SHDN}	---	---	230	800	ns

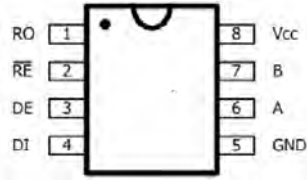
Note 1: All currents into the device are positive; all currents out of the device are negative. All voltages are referred to device ground unless otherwise noted.

Note 2: ΔV_{OD} and ΔV_{OC} are the changes in V_{OD} and V_{OC} , respectively, when the DI input changes state.

Note 3: Maximum current level applies to peak current just prior to foldback-current limiting; minimum current level applies during current limiting.

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Pin Assignment



SOP8

Pin Description

PIN	NAME	FUNCTION
1	RO	Receiver Output, When RE is low and if $A - B \geq -50\text{mV}$, RO will be high; if $A - B \leq -200\text{mV}$, RO will be low.
2	/RE	Receiver Output Enable. Drive RE low to enable RO; RO is high impedance when RE is high. Drive RE high and DE low to enter low-power shutdown mode.
3	DE	Driver Output Enable. Drive DE high to enable driver outputs. These outputs are high impedance when DE is low. Drive RE high and DE low to enter low-power shutdown mode.
4	DI	Driver Input. With DE high, a low on DI forces noninverting output low and inverting output high.
5	GND	Ground
6	A	Noninverting Receiver Input and Noninverting Driver Output
7	B	Inverting Receiver Input and Inverting Driver Output
8	VCC	Positive Supply

Function Tables

● TRANSMITTING

INPUTS			OUTPUTS	
/RE	DE	DI	A	B
X	1	1	1	0
X	1	0	0	1
0	0	X	High-Z	High-Z
1	0	X	Shutdown	

● RECEIVING

INPUTS			OUTPUT
/RE	DE	A-B	RO
0	X	$\geq -0.05\text{V}$	1
0	X	$\leq -0.2\text{V}$	0
0	X	Open/shorted	1
1	1	X	High-Z
1	0	X	Shutdown

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Test circuit

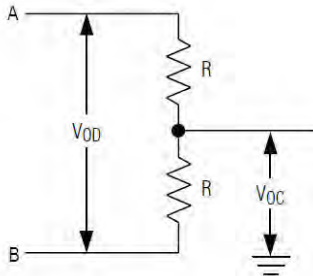


Figure 1. Driver DC Test Load

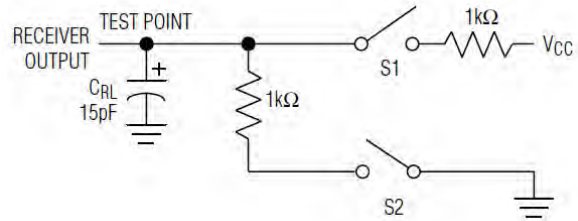


Figure 2. Receiver Enable/Disable Timing Test Load

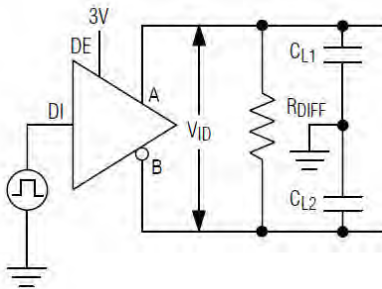


Figure 3. Driver Timing Test Circuit

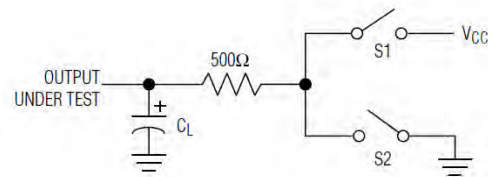


Figure 4. Driver Enable/Disable Timing Test Load

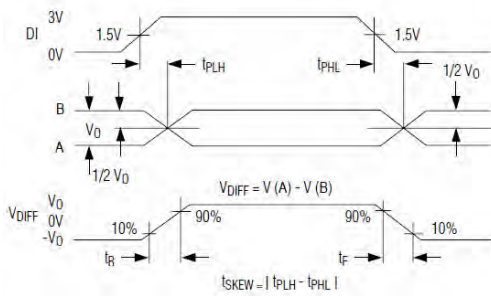


Figure 5. Driver Propagation Delays

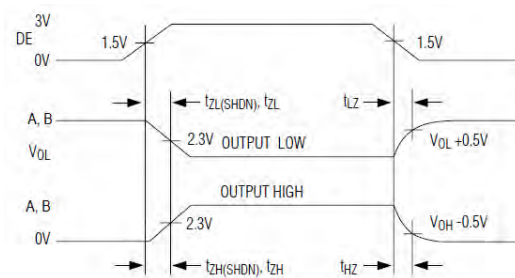


Figure 6. Driver Enable and Disable Times

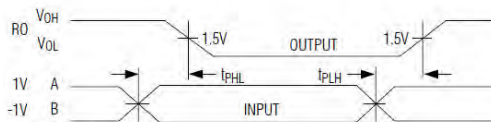


Figure 7. Receiver Propagation Delays

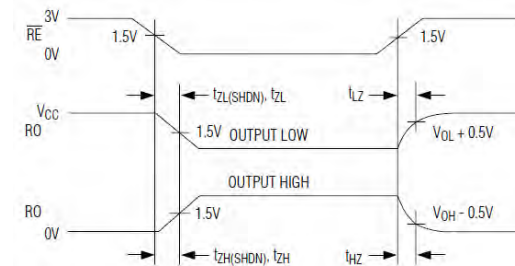
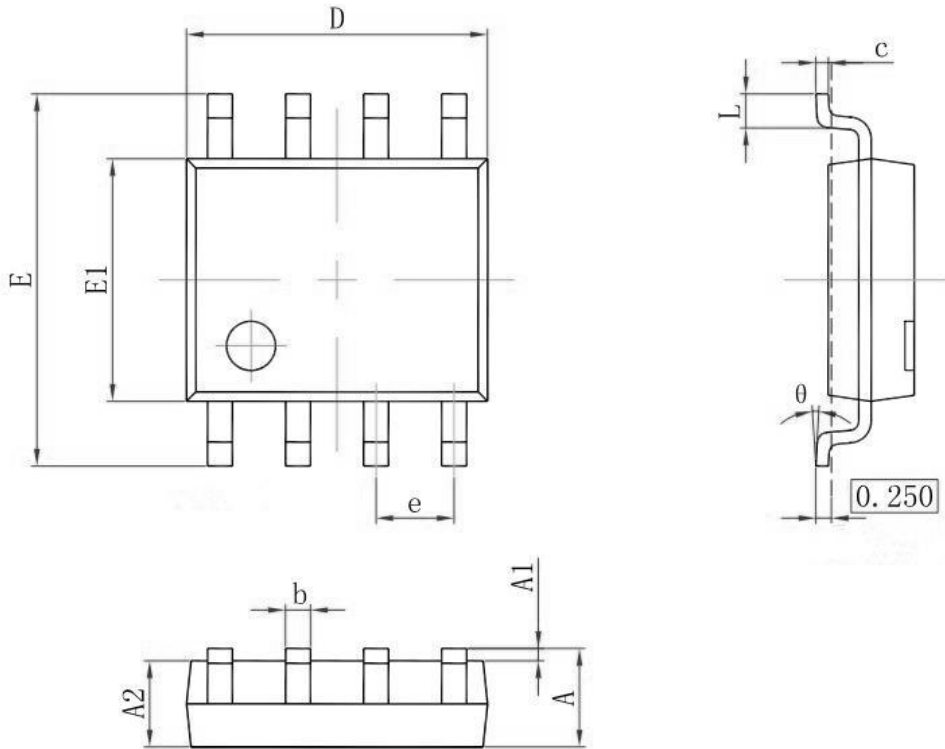


Figure 8. Receiver Enable and Disable Times

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SOP8 Package Information



Symbol	Dimensions In Millimeters		Dimensions In Inches	
	Min	Max	Min	Max
A	1.350	1.750	0.053	0.069
A1	0.100	0.250	0.004	0.010
A2	1.350	1.550	0.053	0.061
b	0.330	0.510	0.013	0.020
c	0.170	0.250	0.007	0.010
D	4.800	5.000	0.189	0.197
e	1.270 (BSC)		0.050 (BSC)	
E	5.800	6.200	0.228	0.244
E1	3.800	4.000	0.150	0.157
L	0.400	1.270	0.016	0.031
θ	0°	8°	0°	8°